



Fast Particles in Fusion Plasmas and present-day experiments

Advanced Plasma Physics Courses, IPP Garching, 2020

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sources and creation of a super-thermal particle population
particle motion in 2D and 3D systems, effect of static
perturbations

- •linear physics of resonant phenomena:
 - I. Experimental evidence
 - 2. Alfvén waves, models, resonant excitation, codes
 - 3. Energetic particle modes
 - 4. n=1 modes
- non-linear phenomena and EP transport
 - I.perturbative regime
 - 2.adiabatic regime
 - 3.non-adiabatic regime



plasma text books and lectures: Wesson, Stroth, Zohm, Guenter,...

R.Fitzpatrick: http://farside.ph.utexas.edu/teaching/plasma/Plasmahtml/

other courses: J.VanDam (IFS): <u>http://home.physics.ucla.edu/calendar/</u> <u>conferences/cmpd/talks/vandam.pdf</u>

experimental overview:

http://www.physics.uci.edu/~wwheidbr/papers/Basic.pdf

theoretical overviews:

- Chen & Zonca: Physics of Alfvén waves and energetic particles in burning plasmas, RMP 2016
- Breizman & Sharapov: 'Major Minority', PPCF 2011
- Ph. Lauber: Phys Rep, 2013
- Y. Todo, [2020]

these slides can be found @ http://www2.ipp.mpg.de/~pwl/





superthermal ('fast') particles in magnetised fusion plasmas



external wave heating (electron or ion cyclotron resonance) injection of a beam of energetic neutral particles (NBI)



ion cyclotron launcher at JET(Culham, UK)

neutral beam boxes at ASDEX Upgrade, Garching

 $\omega_c = eB/m$



- in addition to thermal , i.e. Maxwellian background in a fusion relevant plasma there are highly energetic particles with:
 - high temperature: T_{EP} >> Ti, Te
 - small density: n_{EP} << ne,in
 - pressure ~ $(nT)_{EP}$ ~ $(nT)_{back}$
- can be non-Maxwellian: slowing down distribution
- or anisotropic in parallel velocity (NB) or pitch angle (ICRH)
- energetic fusion α profile is peaked in the plasma centre





- produced with rate $\partial N/\partial t = n_D n_T$ < σv > at peaked at energy=3.5MeV
- particles slow down via Coulomb collisions - smooth distribution in time T_s (slowing down time)
- after some longer time T_M the particles thermalise against electrons and ions to become Maxwellian at $T_{\alpha}=T_{D,T}$
- confinement time for α 's: τ_{α} ;
- in steady state, there are two αpopulations: slowing down α's and thermal α-ash
- $\tau_{\alpha} \sim 10 \tau_{M} \sim 1000 \tau_{s;}$; α 's have time to thermalise: He-ash problem



$$P_{fus} \propto n^2 \langle \sigma v \rangle \sim n^2 T^2 \propto p^2$$





Assume that we have a constant heating input or fusion power - how does the distribution function of the energetic ions looks like after 'sufficient' long time? What determines this time(s) T_s ?

abilangen. Es gill abo. prosteni retationes. tivgeschwindigkeit und vom Streuwinkel abhängen kann. 8.1 Streuung im Coulomb-Potential Coulomb Beziehungen 245ABBILDUNG 8.1; Streuung zweier gleich geladener -Funktionen repräsentieren Impuls- Sellevergieterketkenschwindigweitert Befstientleeilch Die von . Daher ändern sich hier die Einheiten von <u>. Num verwenden wir, dass das Streu-</u> folgt. nun, wenn man-bedenkt, dass bei Integrationen die probler**s matitionen keine der Rela**tivgeschwindigkeit und vom Streuwinkel abhängen kann. Mit und scattering und die Relativgeschwindigkeit dies liniert durch Die Schwerpunktsgeschwindigkeit ist definiert durch Was von der Streufunktich übrig bleibt ist der differenzielle large angle (ions or electrons) folgt nun, wenn man bedenkt, dass dei Integrationen die Funditionduriwirkkhosse Aus 8.14 und unter Dier Wierkholmg kann man auch durch folgende anschaulich small angle -hedAbb. 18 2 de ZRebæregenenvistigliet Ratechton Stolsprozesser **scattering** Was von der Streufunktion übrig bleibt ist den Raumwinkel d. führen wenn genau ein die Einheit m /sr hat. Verfügung steht bleichen dort sind d. die Teilehenflussdic Piegerander Bereicher Bereichter der State streichter State Bereichter Bereichter Bereichter Bereichten stegen m he Abber 8.2 bzwz. Kleinwinkelstreuung im Belle Wirkungsgreichter die reduzierte Masse he Abber 8.2 bzwz. Kleinwinkelstreuung im Belle Wirkungsgreichter die tzentsprichte unter State voor Fläc Teilchen Rincherfordenwinkel derführen wenzerawein Streuzestrum Zeilchen zurotentia Verfitzeiner winhin Alabes Asitlustriertl aus deliedineil die Hussrändhneden Stokparamétekas Stifut/nd differential cross section itt dodut. Won Alzimut – ab und es ist du = ON/nd zentninktennellächen. die zelischetigen chroken Istopparameter och stigter führtestreut zu m Schwerburktsystem sind die Impulsbeträge der beider werden. Der Wirkungsquerschnitt enterpricturgen onder führteste Altiger in asymptotischen Fals, werm in Verbindung steht. Wegen der Synchetric des Potentials hängt der Wäckungsquer-Die Größe d hat die Einheit m und gibt die Fläche an, durch die Schnitt nicht vom Azimut ab und es ist d $\Omega = 2\pi \sin \chi d\chi$. Nach Abb. 8,2 kann man die DRelativgeschwieidigkeiterumeissels, um in den Winkel gestreut zu w



durchgeführt. Dies erfolgt d menden Geschwindigkeiten calculate²⁵⁰dynamical friction wobei wir etzt wieder

8 Transportprozesses

8.34, von dem nur

Trangp Or

8.1 Streuung im Coulomb-Pottential Wegen 8.38 lässt sich der gesamte Tensor

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Integral über die Verseilungsfundtionen Teichen f wed Testteilchen genannt. Man kann bei dadurch noch beliebige Kombinat Opkringen eine State Belle sollte man sich an die Man keines

die zeitliche Imm s. B.40 Isandemonded of Forteric berger and berger of the service hand von Abb. 8.6 Wollen wir die Bedarung Gerander in die Grand von Abb. 8.6 Wollen wir die Bedarung Gerander in die Gerander

-Zusammen mit der Funktione reitliche Impulsönderung des Tysterlichens

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Der Term darf vernæingsführter Damitefolgte förrahle Gas im thermischen Gleiche zu hoch ist keV. Wir führen etstatigter Engligiet terne strecht Franzen terne fürster in der Egile und versinfachen die Gleichung zu Hier ist Geschwindigkeit das Verhältnis der Geschwindigkeit von Teilcher zur ersten Ordnung entwicken. Es folgt: Türzdie benötigten A .h (**§**.8 dE/dt (ke∕**/**3) lon → lonen $-0.025 \text{Die Einheiten sind: Temperatur fin kW, Masse in <math>\pi^2 e^{\sqrt{2}\pi}$ 1.5 1.85ie beidennarer energy of beam ions[keV] 2 kaRerenkaichomszein en Darin . $\frac{1}{2} \frac{1}{2} \frac{1}$ $tze^{E}equerch \begin{cases} 9\pi Z_i^4 m_i \left(n_i \ln \Lambda_i \right)^2 \\ 10m_e^{7.8} und vereinfachen die Gleichurg zwie schnell Tein Telsha wird durch die Tokker-Franck-Gleichurg zwie schnell Tein Telshek ground vereinfachen die Gleichurg zwie schnell Tein Telshek ground vereinfachen die Schnell Tein Telshek ground vereinfa$ inien bei keV. Mit dieser Definit ind vansed Course Frage Und the state of the stat

Slowing down times and free mean path







in addition: Ion cyclotron resonance heating



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geometry: the Tokamak





q= number of toroidal field line turns number of poloidal field line turns

existence of flux surfaces: radial coordinate $\boldsymbol{\Psi}$

∇p=**j**×**B**



motion mainly along the magnetic field line

curvature and gradients of the B field cause perpendicular drifts

passing and trapped particles



Mirror condition:
$$\frac{v_{\parallel}^2(B_{\min})}{v_{\perp}^2(B_{\min})} < \frac{B_{\max}}{B_{\min}} - 1$$

Mirror condition for magnetic surface r:

$$\frac{B_{max}}{B_{min}} - 1 = \frac{B_0(R_0 + r)}{B_0(R_0 - r)} - 1 = \frac{1 + r/R_0}{1 - r/R_0} - 1 = \frac{2r/R_0}{1 - r/R_0}$$

$$\epsilon/\mathsf{R} <<1: |\frac{v_{\parallel}}{v_{\perp}}| < \sqrt{2\epsilon}$$

$$\hat{n}_A = \hat{e}_r = \begin{pmatrix} \sin\vartheta & \cos\varphi \\ \sin\vartheta & \sin\varphi \\ \cos\vartheta \end{pmatrix}$$

Fraction of trapped particles

$$\frac{n_t}{n} = \frac{1}{4\pi} \int_0^{2\pi} d\phi \int_{-\sqrt{2\epsilon}}^{\sqrt{2\epsilon}} \cos\theta d\theta = \frac{1}{2} \Big(\sin\sqrt{2\epsilon} - \sin\left(-\sqrt{2\epsilon}\right) \Big) \approx \sqrt{2\epsilon}$$

Estimate banana width:

i.e. deviation from magnetic surface (assume v_{\parallel} small):

$$\left|\vec{v}_{D}\right| = \left|\frac{m}{qB^{3}}\left(v_{\parallel}^{2} + \frac{1}{2}v_{\perp}^{2}\right)\vec{B} \times \nabla B\right| = \frac{m}{eBR}\left(v_{\parallel}^{2} + \frac{1}{2}v_{\perp}^{2}\right) \approx \frac{m}{2eBR}v_{\perp}^{2}$$

banana width

Banana width~ $v_D \Delta t$ (Δt :time to sample a banana orbit)

Time to complete a banana orbit: $v_{\parallel} \times L$ (length of a field line)



Banana width:
$$w_B = v_D \Delta t = \frac{mv_\perp}{eB} \frac{q}{2} \frac{v_\perp}{v_\parallel} \Delta \theta = r_L \frac{q}{2} \frac{v_\perp}{v_\parallel} \Delta \theta$$

Maximal banana width: $\Delta \vartheta = \pi$, corresponds to $v_{\parallel}/v_{\perp} = \sqrt{2\epsilon}$

$$w_B = r_L \frac{\pi}{2\sqrt{2}} \frac{q}{\sqrt{\epsilon}} \approx r_L \frac{q}{\sqrt{\epsilon}}$$

trapped and passing guiding centre orbits





width of passing orbits: wB/2

toroidal precession of a banana orbit



 P_{φ}





adiabatic invariants (expand Hamiltonian in asymptotic series)

many non-standard orbits possible:

with axissymmetry: stagnation orbits, potatoe orbits



breaking axissymmetry:super-banana orbits (field ripple)





IPP

Poincare plots of particle orbits in presence of perturbations



[Ascot]

•w~√A

 overlapping islands form stochastic regions





symmetry breaking decreases EP confinement

 P_{Φ} not a constant of motion any longer

[AUG, Suttrop]

static perturbations: field ripple, ELM coils, magnetic islands leads to stochastic particle orbits





ITER, I5 MA scenario: alpha particles outside

ψn> 0.7 are not confined since field lines
 can become stochastic
 exact number and wall load depends on
 details like model for field penetration,
 ferritic inserts and coil currents/phase



Results of F3D OFMC calculation



ELMC field increase fast ion loss. NB loss is larger than alpha Heat load appears in divertor region.

ELMC field is essential for loss

Considered that optimized magnetic field perturbation is effective in deterioration

Note: shielding effect of plasmas on field penetration is not considered

Fast ion species	Magnetic field	Loss power fraction [%]	Maximum heat load [MW/m ²]
alpha	Case1: TF ripple alone	0.8	0.06
By NB	^C F1 ^{e1} TE ripple alon on loss	0.8	0.02
alpha	Case2. TF ripple + FI	0.04	<0.01
By NB	Case2: TF ripple + FI	0.05	<0.01
albha	Case3: TF ripple + FI + Min_n4	0.95	0.06
B/ NB	Case3: TF ripple + FI + Min_n4	7.5	0.27
alpha	Case4: TF ripple + FI + Min_n3	1.6	0.06
B/ NB	Case4: TF ripple + FI + Min_n3	10.0	0.21
alpha	Case5: TF ripple + FI + Max_n4	6.2	0.21
B/ NB	Case5: TF ripple + FI + Max_n4	26.2	0.36
alpha	Case6: Axisymmetric TF + Min_n4	0.9	0.06
By NB	Case6: Axisymmetric TF + Min_n4	7.0	0.24
By NB	Case7: Axisymmetric TF + (n=4, 30kAt, zero phase difference between upper, middle, lower coils)	0.6	0.03
BY NB	Case8: Axisymmetric TF + (n=4, 15kAt)	2.4	0.09
P2-10 K. Shinohara et al.			

[NF, 2011]

[steady state scenario:Tani, NF 52, 2012]

[Ascot 2012-2016]: plasma response is not dramatically changing the losses, RMPs can



Magnetic field ia a stellarator: W7-X





courtesy: M. Borchardt









orbits with drifts and radial electric field (W7-X)





H. Patten et al. Plasma Phys. Control. Fusion, 60 085009 (2018)





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 remove helium ash from hot core
 Alfvén spectroscopy: frequency and localisation of mode allows to determine important plasma parameters (e.g. current profile)











magnetic spectrogram ,ASDEX Upgrade #25506



[M Maraschek]

many modes with different characteristics are detected at the plasma edge - global, electromagnetic perturbations toroidal and poloidal mode number analysis possible

temperature fluctuations: electron cyclotron emission imaging (ECEI)





IPP

fluctuations in radiated soft X-ray spectrum:



Soft X-ray (central channel)



determination of radial position



[V Igochine]



The Fast Ion Loss Detector
















- •reflectometry: frequency hopping mode: cut-off density and profile shape play crucial role important for determination of mode position
- interferometry
- collective Thomson scattering
- •γ-ray spectroscopy
- neutron measurements
- •neutral particle analyser; imaging NPA



fast particle driven GAE in W7-AS



#39029





A. Weller et al. 12th International Stellarator Workshop, Sep 27 - Oct 1, Madison, USA, 1999











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"Father of Plasma Physics"

- Hannes Olof Gösta Alfvén
 - Born May 30, 1908 (Norrköping, Sweden); died April 2, 1995
- Career at a glance:
 - Professor of electromagnetic theory at Royal Institute of Technology, Stockholm (1940)
 - Professor of electrical engineering at UCSD (1967-1973/1988)
 - Nobel Prize (1970) for MHD work and contributions in founding plasma physics



Hannes Alfvén received the Nobel Prize in Physics in 1970 from the Swedish King Gustavus Adolphus VI

[J.VanDam]



Huge Influence

- Contributions to plasma physics
 - Existence of electromagnetic-hydromagnetic ("Alfvén") waves (1942)
 - Concepts of guiding center approximation, first adiabatic invariant, frozen-in flux
 - Acceleration of cosmic rays (--> Fermi acceleration)
 - Field-aligned electric currents in the aurora (double layer)
 - Stability of Earth-circulating energetic particles (--> Van Allen belts)
 - Effect of magnetic storms on Earth's magnetic field
 - Alfvén critical-velocity ionization mechanism
 - Formation of comet tails
 - Plasma cosmology (Alfvén-Klein model)
 - Books: Cosmical Electrodynamics (1950), On the Origin of the Solar System (1954), Worlds-Antiworlds (1966), Cosmic Plasma (1981)
- Wide-spread name:
 - Alfvén wave, Alfvén layer, Alfvén critical point, Alfvén radii, Alfvén distances, Alfvén resonance, ...







- His youthful involvement in a radio club at school later led (he claimed) to his PhD thesis on "Ultra-Short Electromagnetic Waves"
- He had difficulty publishing in standard astrophysical journals (due to disputes with Sydney Chapman): Fermi "Of course" (1948)
- He considered himself an electrical engineer more than a physicist
- He distrusted computers
- The asteroid "1778 Alfvén" was named in his honor
- He was active in international disarmament movements
- The music composer Hugo Alfvén was his uncle



[J.VanDam]

start: MHD equations



combine into: $\begin{pmatrix}
\omega^2 - k^2 V_A^2 - k^2 V_S^2 \sin^2 \theta & 0 & -k^2 V_S^2 \sin \theta \cos \theta \\
0 & \omega^2 - k^2 V_A^2 \cos^2 \theta & 0 \\
-k^2 V_S^2 \sin \theta \cos \theta & 0 & \omega^2 - k^2 V_S^2 \cos^2 \theta
\end{pmatrix}
\begin{pmatrix}
V_x \\
V_y \\
V_z
\end{pmatrix} = \mathbf{0}.$

$$v_{A} = \sqrt{\frac{B_{0}^{2}}{\mu_{0} \rho_{0}}} \qquad \qquad v_{S} = \sqrt{\frac{\Gamma p_{0}}{\rho_{0}}} \qquad \qquad \Theta: \text{angle between } k \text{ and } B_{0}$$

[Fitzpatrick, lectures www]

Solubility condition: Det[M]=0

$$\begin{pmatrix} \omega^2 - k^2 V_A^2 - k^2 V_S^2 \sin^2 \theta & 0 & -k^2 V_S^2 \sin \theta \cos \theta \\ 0 & \omega^2 - k^2 V_A^2 \cos^2 \theta & 0 \\ -k^2 V_S^2 \sin \theta \cos \theta & 0 & \omega^2 - k^2 V_S^2 \cos^2 \theta \end{pmatrix} \begin{pmatrix} V_x \\ V_y \\ V_z \end{pmatrix} = \mathbf{0}.$$

$$(\omega^2 - k^2 V_A^2 \cos^2 \theta) \left[\omega^4 - \omega^2 k^2 (V_A^2 + V_S^2) + k^4 V_A^2 V_S^2 \cos^2 \theta \right] = 0.$$

 $\omega = k V_A \cos \theta$,

$$\omega = kV_+,$$

$$\omega = k V_{-},$$

$$V_{\pm} = \left\{ \frac{1}{2} \left[V_A^2 + V_S^2 \pm \sqrt{(V_A^2 + V_S^2)^2 - 4 V_A^2 V_S^2 \cos^2 \theta} \right] \right\}^{1/2}.$$

I.root: Alfven wave, 2nd and 3rd root: coupled waves with coupling strength $v_s^2/v_A^2 \sim \beta/2$

[fitzpatrick, lectures www]

3 roots of dispersion relation:



[fitzpatrick, lectures www]



dispersion relation: $\omega = k_{\parallel} v_A$; periodic cylinder: phase mixing, i.e. strong damping

$$k_{\parallel} = \frac{1}{R_0}(n - \frac{m}{q(r)}); \quad v_A(r) = B(r)/\sqrt{\mu_0 m_i n(r)}$$

n:'toroidal' mode number m: poloidal mode number











global mode structure in the gap



weakly damped











Advanced Courses EP, 2020

MAE

HAE

[D.Spong,2003]

 $\pm 1, \pm 2, ...$

 $\pm 1, \pm 2, ...$

0

 $|\delta_{\rm m}| \ge 1$

Mirror Alfvén eigenmode

Helical Alfvén eigenmode







Reversed shear' Alfvén Eigenmodes (RSAE)







radius

off axis peaked current profile: "advanced tokamaks" - steady state

- \Rightarrow q-profile has minimum
- ⇒ region without continuum damping [Berk, Breizman, Fu, Sharapov, Konovalov, Lauber 2000-2006]

further gaps due to geodesic curvature and coupling between Alfvén and acoustic waves (see below)







gaps scale with plasma beta:

- $\beta = \frac{\text{kinetic pressure}}{\text{magnetic pressure}}$
- ⇒ beta induced Alfvén eigenmode : BAE
- ⇒ beta induced Alfvén- Acoustic

eigenmode : BAAE strongly modified in kinetic description! (ω~ω_{t,b})

MHD BAAE cannot be excited - strongly damped;

drift-Alfvén-type instabilities at rational surfaces -

can be excited by thermal gradients

[Heidbrink 1992, Zonca 1996, Gorelenkov 2006, Lauber 2013, Heidbrink 2020] Advanced Courses EP, 2020 IPP

Resonant drive:











- coupling is approximately given by the structure of B ⇒ investigate spectrum of B
- note, that for a TAE in a large aspect ratio tokamak: $\frac{\gamma}{\omega_0}$ is independent of the equilibrium

• the resonance condition $\omega - k_{||}v_{th} = 0$ determines

$$v_{m'n'}^{\text{res}} = v_A \left| 1 \pm \frac{m'\iota^* + n'N_p}{m\iota^* + n} \right|^{-1}$$

i.e. well known resonances at $v_0 = v_A$ and $v_0 = v_A/3$ for a Tokamak

extract possible coupling from B spectrum





W-AS

IPP

W7-X



W7-AS A. Weller et al., Phys. Plasmas, **8**, 931 (2001):



W7-X:

equilibrium:

M. Drevlak et al., Nucl. Fusion, **45**, 731 (2005): from PIES calculation: practically island free



mode:









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Kinetic Description Vlasov, Fokker-Planck Equation





the gyrokinetic model

[Littlejohn, Hahm, Brizard,Qin 1983-2006]



gyro frequency >> wave frequency

 \Rightarrow decouple/average out gyromotion from the rest of the particle's motion

$$\mathcal{L}(\mathbf{A},\phi) = \int d^3 \mathbf{x} \left(\frac{\epsilon_0 \mathbf{E}^2}{2} - \frac{\mathbf{B}^2}{2\mu_0} \right) + \int d^3 \mathbf{x} \left(\mathbf{j} \cdot \mathbf{A} - \rho \phi \right).$$

coordinate transform in two small parameters:

I. $\rho_i / L_B \Rightarrow$ guiding centre coordinates

2. separation of perturbed and equilibrium potentials/ fields \Rightarrow "drifting rings"

⇒consistent model, energy conservation





gyro-angle averaging:

$$\frac{1}{2\pi} \int d\bar{\xi} e^{\pm \boldsymbol{\varrho} \cdot \nabla} = \frac{1}{2\pi} \int d\bar{\xi} e^{\pm \boldsymbol{\varrho} \nabla_{\perp} \cos \bar{\xi}} = J_0 \Big(\frac{\boldsymbol{\varrho} \nabla_{\perp}}{i} \Big),$$



quasi-neutrality: $0 = \sum_{a} e_{a} \left[\int J_{0} f d^{3} v + \int \frac{e_{a} \phi}{T_{a}} F_{0} (J_{0}^{2} - 1) \right]$

n mal in ITER: eare Selbstheizung des Plasmas



combine Ampère's law with 0-th order moment of GK equation to arrive at:

linear model equations containing crucial effects for self-consistent description of EP driven modes:

gyrokinetic equation: propagator \rightarrow resonance $h = \frac{ie}{T} F_0 \sum_m \int_{-\infty}^t dt' e^{i[n(\varphi'-\varphi)-m(\theta'-\theta)-\omega(t'-t)]} e^{-im\theta} \cdot (\omega - \omega_*^T) J_0 \cdot \left[\phi_m(r') - (1 - \frac{\omega_d(\theta')}{\omega})\psi_m(r')\right]$ free energy

quasi-neutrality:

$$\sum_{a} \frac{e_a^2 n_a}{T_a} \Big[\varrho_a^2 \nabla_{\perp}^2 \Big] \phi + e_a \int J_0 f \ d^3 \mathbf{v} = 0; \quad \mathbf{E} = -\nabla \phi - \frac{\partial \mathbf{A}}{\partial t}; \quad A_{\parallel} = \frac{1}{i\omega} (\nabla \psi)_{\parallel}$$

gyrokinetic moment equation: shear Alfven law

$$-\frac{\partial}{\partial t} \left[\nabla \cdot \left(\frac{1}{v_A^2} \nabla_\perp \phi \right) \right] + (\mathbf{B} \cdot \nabla) \frac{\nabla \times \nabla \times \frac{c}{i\omega} (\nabla \psi)_{\parallel}}{B^2} + \left[\frac{1}{i\omega} \nabla (\nabla \psi)_{\parallel} \times \mathbf{b} \right] \cdot \nabla \frac{\mu_0 j_{0\parallel}}{B}$$
$$= -\sum_a \mu_0 \int d^3 v (e \mathbf{v}_d \cdot \nabla J_0 f)_a + \frac{3}{4} \frac{\mu_0 e_a^2 n_a}{T_a} \varrho_a^4 \nabla_\perp^4 \frac{\partial}{\partial t} \phi + \sum_a \frac{m_a n_a}{m_i n_i} \frac{\omega_a^*}{v_A^2} \nabla_\perp^2 \phi$$

'pressure' tensor - curvature drift coupling

[LIGKA model]

reduced MHD as limit

in toroidal geometry: coupling via curvature drifts:

combine with QN (Φ - ψ) \Rightarrow dispersion relation (no fast ions):

$$\sum_{m} \omega^{2} \left(1 - \frac{\omega_{*p}}{\omega} \right) - k_{\parallel}^{2} \omega_{A}^{2} R_{0}^{2} = 2 \frac{v_{thi}^{2}}{R_{0}^{2}} \left(- \left[H(x_{m-1}) + H(x_{m+1}) \right] + \left[\frac{N^{m}(x_{m-1})N^{m-1}(x_{m-1})}{D^{m-1}(x_{m-1})} + \frac{N^{m}(x_{m+1})N^{m+1}(x_{m+1})}{D^{m+1}(x_{m+1})} \right] \right)$$

well-known dispersion relation [Zonca 1996,2009, Lauber 2009]

=local solution of linearised GK set of equations [LIGKA model]

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global solutions: local and non-local damping







local and non-local damping







Eigenmoden einer Stradivari



Stradivari frequency response [Jansons,2004]





eigenmodes in a Tokamak, low toroidal/poloidal mode number



frequency response of ASDEX Upgrade (using linear GK model)







Scan throughout the gap region

in order to find all the modes in and around a gap: drive perturbation at plama boundary, sweep frequency and measure plasma response




IPP

Kinetic TAEs





two KAWs propagating in opposite directions form a standing wave: KTAE

EUTERPE:

- gyrokinetic simulations for stellarators
- nonlinear, electromagnetic
- global simulation domain: full flux-surface, full radius treatment of non local effects: e.g. profiles, neoclassical electric field
- multiple kinetic species: ions, electrons, fast ions/impurities
- pitch angle collision operator
- includes models of differing complexity: EUTERPE (full kinetic) FLU-EUTERPE (electron fluid hybrid) CKA-EUTERPE (perturbative fast particle interaction) relative to HAGIS/LIGKA (tokamak): similar model

requires experts to run and to evaluate results (no black-box code)

run time depends on the case: hours to days on 32-512 processors

relative to ORB5 (tokamak): similar numerical techniques











- PIC: charge and current calculated on grid using markers
- 4th order Runge-Kutta scheme to solve gyrokinetic equations of motion in phase space.
- Mixed variables formulation: mitigation of cancellation problem Mishchenko A, Könies A, Kleiber R and Cole M 2014 Phys. Plasmas 21 092110

$$\frac{\partial f_{1s}}{\partial t} + \dot{\mathbf{R}} \cdot \frac{\partial f_{1s}}{\partial \mathbf{R}} + \dot{v}_{\parallel} \frac{\partial f_{1s}}{\partial v_{\parallel}} = -\dot{\mathbf{R}}^{(1)} \cdot \frac{\partial F_{0s}}{\partial \mathbf{R}} - \dot{v}_{\parallel}^{(1)} \frac{\partial F_{0s}}{\partial v_{\parallel}}$$

$$\int \frac{q_i F_{0i}}{T_i} \left(\phi - \langle \phi \rangle \right) \delta(\mathbf{R} + \boldsymbol{\rho} - \mathbf{x}) \, \mathrm{d}^6 Z = \bar{n}_{1i} - \bar{n}_{1e}$$
$$\left(\frac{\beta_i}{\rho_i^2} + \frac{\beta_e}{\rho_e^2} - \nabla_{\perp}^2 \right) A_{\parallel}^{(\mathrm{h})} - \nabla_{\perp}^2 A_{\parallel}^{(\mathrm{s})} = \mu_0 \left(\bar{j}_{\parallel 1i} + \bar{j}_{\parallel 1e} \right)$$

Global, non-linear, collisional, δf , neglects δB_{\parallel}





• linearized equations of reduced MHD transformed to an eigenvalue problem:

$$\begin{split} \omega^{2} \left[\nabla \cdot \left(\frac{1}{v_{A}^{2}} \nabla_{\perp} \phi \right) + \frac{3}{4} \nabla \nabla_{\perp} \left(\rho_{i}^{2} \frac{1}{v_{A}^{2}} \nabla \cdot \nabla_{\perp} \phi \right) \right] = & - \nabla \cdot \left[\mathbf{b} \nabla^{2} (\mathbf{b} \nabla) \phi \right] \\ & - \nabla \cdot \left[\mathbf{b} \nabla \left(\mu_{0} \frac{j_{\parallel}}{B} \mathbf{b} \times \nabla \Phi \right) \right] - \nabla \cdot \left[\frac{\mu_{0} p_{\perp}^{(1)}}{B^{2}} \mathbf{b} \times \nabla B \right] - \nabla \cdot \left[\frac{\mu_{0} p_{\parallel}^{(1)}}{B^{2}} \mathbf{b} \times \nabla B \right] - \nabla \cdot \left[\frac{\mu_{0} p_{\parallel}^{(1)}}{B^{2}} \mathbf{b} \times \kappa \right] \end{split}$$

- The CKA code is used to solve the MHD equations in 3D real magnetic geometry
- Determines the mode frequency ω and the mode structure $\phi(r), A_{||}(r)$

$$E_{||} = -\nabla \phi - \frac{\partial A_{||}}{\partial t} = 0$$

- B-splines in all three directions, direct eigenvalue solvers from PETSc/SLEPc framework
- phase factor isolating a dominating Fourier mode as in EUTERPE

₩

- uses mode structure $(A_{||}, \phi)$ and frequency from CKA code
- evolves Vlasov or Fokker-Planck equation in the EUTERPE framework for fast particles in the given field
- \bullet evolves amplitudes and phases of $(A_{||},\,\phi)$ according to the mode evolution equations
- v_{\parallel} -formulation of GK equations

Alfvén eigenmodes in stellarators: critical beta











TAE mode frequencies and growth/ damping rates from a local computation







similar to CKA-EUTERPE, in 2D

difference: non-perturbative mode structures with $E_{//} \neq 0$ new: IMAS capabilities; various local and global models consistently embedded for time-dependent scenario analysis







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- for strong drive (steep gradients), modes in the Alfvén continuum can be driven
- mode frequency purely determined by energetic particles: $\omega \sim \omega_{t,fast}$
- both gap and energetic particle continuum modes can be described with generalised fishbone dispersion relation [Chen, Zonca 2006]
- often bursty behaviour (strong damping!)
- often strongly 'chirping': mode follows fast evolution of gradient in real and phase space ⇒ no time to form eigenmode by radial localisation
- in present day machines usually seen due to strong NBI heating (abrupt large-amplitude event: ALE)
- linear EPM threshold can be determined [A. Koenies, A. Mishchenko] non-linear behaviour very complex [Vlad, Zonca,Briguglio 2006]







the fishbone dispersion relation [Chen, 1984]



$$\sum_{m} \omega^{2} \left(1 - \frac{\omega_{*p}}{\omega}\right) - k_{\parallel}^{2} \omega_{A}^{2} R_{0}^{2} = 2 \frac{v_{thi}^{2}}{R_{0}^{2}} \left(-\left[H(x_{m-1}) + H(x_{m+1})\right] + \tau \left[\frac{N^{m}(x_{m-1})N^{m-1}(x_{m-1})}{D^{m-1}(x_{m-1})} + \frac{N^{m}(x_{m+1})N^{m+1}(x_{m+1})}{D^{m+1}(x_{m+1})}\right]\right)$$

$$- i\Lambda + \delta W_{core} + \delta W_{hot} = 0,$$

$$\delta W_{\text{hot}} \sim \int dE d\mu dP_{\varphi} d\theta d\varphi \sum_{k=-\infty}^{\infty} \frac{\partial F}{\partial E} \frac{(\omega - \bar{\omega}_*)|\mathcal{L}_k|^2}{\omega - \omega_{prec} - (nq - k)\omega_{t,b}}$$

nzione EURATOM ENEA sulla Fusione

 $\delta \hat{W}_{\text{core}} = 3\pi \Delta q_0 \left(\frac{13}{144} - \beta_{ps}^2 \right) \left(\frac{r_s^2}{R_0^2} \right)$ with $\beta_{ps} = -(R_0/r_s^2)^2 \int_0^{r_s} r^2 (d\beta/dr) dr, \ \Delta q_0 = 1 - q(r=0) \text{ and } \beta = \frac{8\pi P}{B_0^2}$



particle- wave- energy- exchange by resonant interaction

$$\delta W_{s} = \frac{\pi}{M_{s}^{2}} \left\{ \sum_{\sigma}^{\infty} \right\} \int ds \int d\varphi \int d\mu \, d\epsilon \left(-\int \frac{d\vartheta}{|v_{||}|} \sqrt{g} B \right) \sum_{\substack{n,m \\ n',m'}} \sum_{p=-\infty}^{\infty} e^{-i\frac{2\pi}{N_{p}}(n'-n)\varphi} \times \left(\frac{\partial F_{s}}{\partial \epsilon} \right)_{\mu} \frac{\omega - 2\pi (\frac{n}{N_{p}}J - mI)\omega^{*}}{m \left\langle \omega_{d}^{\vartheta} \right\rangle + \frac{n}{N_{p}} \left\langle \omega_{d}^{\varphi} \right\rangle + \left\{ \frac{\sigma(p+nq)}{p} \right\} \omega_{\left\{ \frac{t}{b} \right\}} - \omega} L_{m'n'}^{(1)*} \mathcal{M}_{pn}^{m'n'*} L_{mn}^{(1)} \mathcal{M}_{pn}^{mr}$$

definition of $\mathcal{M}_{pn}^{m'n'}$: for passing particles:

perturbed particle Lagrangian:

$$L^{(1)} = -(Mv_{\parallel}^2 - \mu B)\xi_{\perp} \cdot \kappa + \mu B\nabla \cdot \xi_{\perp}$$

$$\mathcal{M}_{pn}^{m'n'} = \left\langle e^{i[2\pi(m'+n'q)\vartheta'' - (p+nq)\omega_t t'']} \right\rangle_{\vartheta''}$$

for reflected particles:

$$\mathcal{M}_{pn}^{m'n'} = \left\langle e^{2\pi i (m'+n'q)\vartheta''} \cos(p\omega_b t'') \right\rangle_{\vartheta''}$$

 $\langle \dots \rangle$ denotes the transit or bounce average



the fishbone dispersion relation [Chen, 1984]



$$-i\Lambda + \delta W_{core} + \delta W_{hot} = 0,$$

 $\begin{array}{ll} \operatorname{Re}[\Lambda^2] < 0 : & \text{gap modes} \\ \operatorname{Re}[\Lambda^2] > 0 : \operatorname{EP modes in continuum} \end{array}$

the combined effect of δW core and Re[δW hot] is to 'move' the mode away from the local continuum solution and determines if the mode can exist -> 'Alfven zoo'

for EPMs, the mode frequency is set by the EPs the drive has to overcome continuum damping i.e. $Im(\delta Whot) > Re(\Lambda)$

theory for linear onset well developed [Zonca PoP, 2005]





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the fishbone cycle







[JET, F. Nabais, 2005]







- reminder: MHD stability of n=1,m=1 ideal kink mode is determined by higher order $O(\epsilon^4)$
- therefore, small, non-ideal terms like the EP pressure can compete
- both situations are possible: stabilisation and destabilisation
- stabilisation: the conservation of the third adiabatic invariant

$$P_{\varphi} = J_3 = e\Psi + \frac{I(\Psi)}{B_{(0)}}mv_{\parallel} \approx e\Psi + Rmv_{\parallel}$$
 'toroidal' moment

corresponds to conservation of poloidal flux through the area described by precessional drift motion in toroidal direction



•adiabaticity condition is fulfilled when precessional drift frequency is fast compared to mode frequency
•if perturbation tries to adiabatically change the flux

- through these orbits, the orbits have to shift or tilt in order to preserve the flux
- •depending on the EP distribution function, this can result a positive work (δ W), i.e. the mode has to do work on the particles, i.e. the EP are stabilising
- •this is the mechanism for sawtooth stabilisation by EPs, i.e. the kink mode that triggers the crash is suppressed





- •if the 3rd adiabatic invariant breaks down, i.e. when EPs are not fast enough compared to mode frequency, the mode can be destabilised
- •in this case the EP radial gradient at the resonance together with the background diamagnetic effects provide a drive for the (1,1) mode
- •two branches: diamagnetic and precessional fishbones;

Fast particle stabilisation

1611

tion of low frequency internal kink modes and the excitation of m = 1 fishbone stability window can be obtained, up to a maximum value of β_p corresponding to maximum stable β_p can exceed significantly the ideal MHD threshold value, wing conditions are met (we restrict ourselves to $p_{\parallel h} \sim \epsilon_s p_{\perp h}$; see Coppi et al, mit):



n=1 fishbone





also a non-bursting n=1 kink mode, so called LLM (long lived mode) was recently observed at MAST and NSTX





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non-linear interaction of several modes







ad in the phase velocities in the packet. The net dispersel rate

IPP

particle losses - synthetic diagnostic







hybrid models predict roughly the flattening of the EP radial profile



[B. Heidbrink, DIII-D, PRL 2010]

[R.White,2011]



- Stored fast ion energy scales as ~ P_{NBI} ^0.53 for P_{NBI} >6.25MW.
- Fast-ion confinement degrades steadily with increasing power but a sharp transition to stiff transport is not observed.

Y. Todo[TCM 2015]: DIII-D case

Evolution of fast ion energy flux brought about by AEs (1)

LASMA SIMULATO

IFERC



using the QL approximation, smaller EP transport was found! Importance of avalanches!







boundaries? for artificially reduced damping or higher EP pressure gradient, EP avalanches are found



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recently confirmed by fully GK non-linear ORB5 simulations







fast-ion drive is insufficient to overcome the background-plasma damping (CKAhybrid model)

C. Slaby et al. Nucl. Fusion 60, 112004 (2020)





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- •electric field of the mode tries to flatten distribution function
- relaxation processes (V) try to reestablish original distribution function
 depending on the balance between the linear drive γ_L and the damping γ_d, four regimes with substantially different EP transport are found:

$$\hat{\boldsymbol{v}} = \boldsymbol{v} / \boldsymbol{\gamma} = \boldsymbol{v} / (\boldsymbol{\gamma}_L - \boldsymbol{\gamma}_d)$$

→linear mode damping/drive is crucially important for non-linear evolution!

<u>lecture series by F. Zonca:</u> <u>http://www.afs.enea.it/zonca/references/seminars/IFTS_spring10/</u>



- [Berk, Breizman, 1992-96; Lilley, 2010]
- a) steady state
- b) periodic modulation
- c) chaotic regime
- d) explosive regime



$\begin{pmatrix} F & F_0 \end{pmatrix}$ complex non-line

- a) steady state
- b) periodic modulation
- c) chaotic regime
- d) explosive regime



#20488, magnetics


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complex non-linear dynamics





holes and clumps form in phase space and propagate while modifying the mode frequency



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phase space structures





dedicated experiments at ASDEX Upgrade (BAE)





qualitative theoretical prediction correct [Ph. Lauber, I Classen, IAEA TCM meeting 2011] quantitative modeling challenging: phase space resolution!

Advanced Courses EP, 2020

classification of parameter space



change of background damping was taken into account: metastable modes



chirping of fast particle driven modes in W7-X





Case 1 has twice the linear growth rate and twice the damping rate compared to case 2.

small drive in W7-X may make chirping parabola small and difficult to observe



C. Slaby et al.Nucl. Fusion 59 046006 (2019)

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mode saturation amplitude analytically scales with $\nu^{2/3}$ (valid if linear growth rate much larger than damping)

- calculations with CKA-EUTERPE
- depend on parameter regime in tokamaks, ω_b seems to determine transition between regimes
- found to be different in W7-X (at least for parameters and modes chosen): saturation regime in W7-X is radial decoupling
- C. Slaby et al. Nucl. Fusion 58, 082018 (2018)





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Energetic ion losses by TAE Avalanche in NSTX



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 $\frac{d\omega}{dt} \ll \omega_b^2$

adiabatic:

trapping frequency of resonant particle in the wave

i.e. particles are trapped long in the wave compared to frequency chirp if violated, the wave can saturate in a few bounce times: ballistic radial transport can occur:



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[HMGC team, Frascati, 2006]

Abrupt Large Event (ALE) at JT60 (NNBI)





n=I TAE burst seem to have some similarity to 'fast sweeping' and 'ALE' at JT-60U







- ECRH is sufficient but not necessary for chirping
- single helicity mode model
- existence of ι window for chirping

measurement using HBIP

A.V. Melnikov et al., Nucl. Fusion 56, 112019 (2016)





- 'errors' in the axisymmetric fields of a Tokamak cause particle losses since EP drift orbits are larger than the thermal particle orbits and have more energy, they are more dangerous for the first wall
- resonant wave-particle interaction can radially redistribute EPs and cause losses
- the damping and the global mode structure is crucial for the linear stability and non-linear saturation of the modes
- the saturation process is very complicated: weakly non-linear and strong non-linear regime show very different behaviour due to the formation of phase space structures and the formation of ballistic avalanches, role of collisions
- role of non-linear mode-mode coupling, excitation of zonal structures
- prediction for ITER/DEMO/HELIAS reactors is challenging which regime is relevant?
- is there overlap between resonant/ballistic core transport and edge losses due to static perturbation fields?





recent progress on several fronts of model validation for EP physics:

- analytical/ semi-analytical models & reduced models that can make contact to analytical descriptions (verification/physics understanding, large parameter range)
- code integration for quantitative predictions (smaller parameter range)
- global EM non-linear GK simulations (restricted parameter range)

to be done: implement EP models in tranport codes (IMAS/WPCD) (large amount of automatisation required)

experimental 'opportunities' for code validation:

- theory/simulation has to drive and trigger experiments for validating models ('exotic' regimes) at present day machines (JET/TCV/ASDEX Upgrade, West,..)
- MAST Upgrade (EP avalanches, low-n though...)
- W7-X
- JET- DT (1-2 years)
- JT60-SA (energetic NNBI) will play important role within next 10 years
- DTT (intermediate n's possible)





Additional slides

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Linear Gyrokinetic model: Qin,Rewoldt,Tang [1999-2006] Ph Lauber [2003-2009]

Starting point: generalised gyrokinetic Maxwell-Vlasov System [Hahm, Brizard, Sugama,...]

$$\left[\frac{\partial}{\partial t} + \{\bar{\mathbf{Z}}, \bar{H}_a(\bar{\mathbf{Z}}, t)\} \cdot \frac{\partial}{\partial \bar{\mathbf{Z}}}\right] F_a(\bar{\mathbf{Z}}, t) = 0$$

Linearise:

$$\begin{bmatrix} \{\bar{\mathbf{Z}}, \bar{H}_{1}(\bar{\mathbf{Z}}, t)\} \cdot \frac{\partial}{\partial \bar{\mathbf{Z}}} \end{bmatrix} F_{a0}(\bar{\mathbf{Z}}) + \begin{bmatrix} \frac{\partial}{\partial t} + \{\bar{\mathbf{Z}}, \bar{H}_{0}(\bar{\mathbf{Z}})\} \cdot \frac{\partial}{\partial \bar{\mathbf{Z}}} \end{bmatrix} f_{a}(\bar{\mathbf{Z}}, t) = 0$$

$$\mathbf{z}_{a} = (\mathbf{x}_{a}, v_{a\parallel}, \mu_{a0}, \theta_{a}) \rightarrow \mathbf{Z}_{a} = (\mathbf{X}_{a}, U_{a}, \mu_{a}, \xi_{a}) \quad \text{guiding-centre}$$

$$\mathbf{Z}_{a} = (\mathbf{X}_{a}, U_{a}, \mu_{a}, \xi_{a}) \rightarrow \bar{\mathbf{Z}}_{a} = (\bar{\mathbf{X}}_{a}, \bar{U}_{a}, \bar{\mu}_{a}, \bar{\xi}_{a}) \quad \text{gyro-centre}$$

work out brackets and use: $E=H_0=mU^2/2 + \mu B$ $\frac{\partial f}{\partial t} + (\bar{U}\mathbf{b} + \mathbf{v}_d) \cdot \nabla f = \frac{c\mathbf{b}}{eB} \cdot (\nabla F_0 \times \nabla H_1) + \frac{\partial F_0}{\partial E} (\bar{U}\mathbf{b} + \mathbf{v}_d) \cdot \nabla H_1$

reminder: curvature drift

$$\frac{\partial f}{\partial t} + (\bar{U}\mathbf{b} + \mathbf{v}_d) \cdot \nabla f = \frac{c\mathbf{b}}{eB} \cdot (\nabla F_0 \times \nabla H_1) + \frac{\partial F_0}{\partial E} (\bar{U}\mathbf{b} + \mathbf{v}_d) \cdot \nabla H_1$$
$$\{\bar{\mathbf{Z}}, H_0\} = -\frac{c\mathbf{b}}{eB} \times (\bar{\mu}\nabla B) + \frac{(\mathbf{B} + \nabla \times \frac{mc}{e}\bar{U}\mathbf{b})\bar{U}}{B} = -\frac{c\mathbf{b}}{eB} \times (\bar{\mu}\nabla B) + \bar{U}\mathbf{b} + \mathbf{V}_d$$
$$\mathbf{V}_d \equiv \frac{cmU}{eB} \nabla \times U\mathbf{b}$$

in order to arrive at usual expression: $\mathbf{v}_d = -\frac{c\mathbf{b}}{eB} \times \left(m\bar{U}^2(\mathbf{b}\cdot\nabla)\mathbf{b} + \bar{\mu}\nabla B\right)$

one has to take into account that:

$$\mathbf{B}_a^* \equiv \nabla \times \mathbf{A}_a^*$$
 and $B_{a\parallel}^* \equiv \mathbf{B}_a^* \cdot \mathbf{b}$.

$$\mathbf{A}_{a}^{*}(\mathbf{X}_{a}, U_{a}, \mu_{a}) = \mathbf{A}_{0}(\mathbf{X}_{a}) + \epsilon_{B} \frac{m_{a}c}{e_{a}} U_{a}\mathbf{b}(\mathbf{X}_{a}) - \epsilon_{B}^{2} \frac{m_{a}c^{2}}{e_{a}^{2}} \mu_{a}\mathbf{W}(\mathbf{X}_{a}),$$

frequency ordering: restrict system to shear Alfvén wave frequencies and below by neglecting the fast wave:

 $\mathbf{A}_1 = A_{\parallel} \mathbf{b}$ or $\mathbf{A}_{\perp} = 0$

 ω_A is small compared to the gyrofrequency,

note: if the fast wave physics and hf physics is needed, the system of equations has to be solved for the perpendicular components of A and a 'gauge' function S containing the gyro-motion (3 more equations!) [gyro-gauge theory, H. Qin, 1999] now: quasi-neutrality and Ampère's law have to be derived by building moments: density, flows, current, pressure,...

GK equation is written in gyro-centre variables! back-transform in real space coordinates needed:

$$D = -4\pi \sum_{a} e_{a} \int d^{6} \bar{\mathbf{Z}} J_{a}(\bar{\mathbf{Z}}) \cdot \delta[\bar{\mathbf{X}} + \bar{\boldsymbol{\varrho}}_{a0}(\bar{\mathbf{Z}}) - \mathbf{x}] \cdot \left(F_{a}(\bar{\mathbf{Z}}, t) + \Delta \frac{e}{B} \tilde{\psi}_{a} \frac{\partial F_{a}(\bar{\mathbf{Z}}, t)}{\partial \mu}\right)$$

 $\phi = \phi_0(\mathbf{x}) + \Delta \phi_1(\mathbf{x}, t)$

$$\widetilde{\phi}_{1}(\bar{\mathbf{X}}_{a} + \epsilon_{B}\bar{\boldsymbol{\varrho}}_{a}, t) = \phi_{1}(\bar{\mathbf{X}}_{a} + \epsilon_{B}\bar{\boldsymbol{\varrho}}_{a}, t) - \langle \phi_{1}(\bar{\mathbf{X}}_{a} + \epsilon_{B}\bar{\boldsymbol{\varrho}}_{a}, t) \rangle$$

$$\widetilde{\mathbf{v}}_{a0} \cdot \mathbf{A}_{1}(\bar{\mathbf{X}}_{a} + \epsilon_{B}\bar{\boldsymbol{\varrho}}_{a}, t) = \bar{\mathbf{v}}_{a0} \cdot \mathbf{A}_{1}(\bar{\mathbf{X}}_{a} + \epsilon_{B}\bar{\boldsymbol{\varrho}}_{a}, t) - \langle \bar{\mathbf{v}}_{a0} \cdot \mathbf{A}_{1}(\bar{\mathbf{X}}_{a} + \epsilon_{B}\bar{\boldsymbol{\varrho}}_{a}, t) \rangle$$

$$\widetilde{\psi}_{a}(\bar{\mathbf{Z}}_{a}, t) = e_{a}\widetilde{\phi}_{1}(\bar{\mathbf{X}}_{a} + \epsilon_{B}\bar{\boldsymbol{\varrho}}_{a}, t) - \frac{e_{a}}{c}\widetilde{\mathbf{v}}_{a0} \cdot \mathbf{A}_{1}(\bar{\mathbf{X}}_{a} + \epsilon_{B}\bar{\boldsymbol{\varrho}}_{a}, t)$$

split off adiabatic part: (symmetry, numerics)

$$f = h + H_1 \frac{\partial F_0}{\partial E} - \left[e \frac{\partial F_0}{\partial E} - \frac{c \nabla F_0}{i \omega B} \cdot (\mathbf{b} \times \nabla)\right] J_0 \psi$$

$$\frac{\partial h}{\partial t} + (U\mathbf{b} + \mathbf{v}_d) \cdot \nabla h \underbrace{\left[\frac{c\mathbf{b}}{eB} \times \nabla F_0 \cdot \nabla \right]}_{eB} \frac{\partial F_0}{\partial E} \underbrace{\partial}_{eD} J_0 [\phi - (1 - \frac{\hat{\omega}_d}{\omega} \psi)] \\ \hat{\omega}_d = \frac{\mathbf{v}_d}{i} \cdot \nabla$$

use Maxwellian distribution function for background electrons and ions

include toroidicity: particle orbits are complicated - use particle tracing to calculate kinetic quantities

$$\hat{h} = ie \sum_{m} \int_{-\infty}^{t} dt' e^{i[n(\varphi'-\varphi)-m(\theta'-\theta)-\omega(t'-t)]} e^{-im\theta}$$
$$\frac{\partial F_{0}}{\partial E} \left[\omega - \hat{\omega}_{*}\right] J_{0} \left[\phi_{m}(r') - \left(1 - \frac{\omega_{d}(r',\theta')}{\omega}\right)\psi_{m}(r')\right]$$

rewrite phase factor in terms of bounce and drift motion: $n(\varphi' - \varphi) - m(\theta' - \theta) = \int_{t}^{t'} dt'' (n \frac{d\varphi}{dt''} - m \frac{d\theta}{dt''})$

$$\omega_D = n(\frac{d\varphi}{dt} - q(r^0)\frac{d\theta}{dt})$$
$$\omega_D^0 = \frac{1}{\tau_{b,t}} \int dt \omega_D; \qquad S_m(r^0) = nq(r^0) - m$$

$$W = W(t) = \int_0^t dt'' \Delta \omega_D; \qquad W' = W(t') = \int_0^{t'} dt'' \Delta \omega_D; \qquad \Delta \omega_D = \omega_D - \omega_D^0$$

integrate over time, expand in 'bounce/transit' harmonics and change to (E,Λ) phase space coordinates:

$$\tilde{n}_{a} = \left(\int J_{0}hd^{3}\mathbf{v}\right)^{circ} = -\frac{\pi}{2}e_{a}v_{th}^{3}\sum_{m}\int_{0}^{b_{min}(r^{0})}\frac{d\Lambda}{b(r,\theta)\sqrt{1-\frac{\Lambda}{b(r,\theta)}}}\int_{0}^{\infty}dY\sqrt{Y}\cdot\sum_{k}\sum_{\sigma}\frac{\partial F_{0}}{\partial E}$$
$$\frac{(\omega-\hat{\omega}_{*})e^{-i[S_{m}^{0}\theta-(H\sigma S_{m}^{0}+k)\omega_{t}\hat{t}]}}{\omega-\omega_{D}^{0}-(H\sigma S_{m}^{0}+k)\omega_{t}}\cdot J_{0}^{2}\left[a_{k,m,\sigma}\phi_{m}(r^{0})-(a_{k,m,\sigma}-a_{k,m,\sigma}^{G})\psi_{m}(r^{0})\right]$$

$$a_{m,k,\sigma} = \frac{1}{\tau_t} \int_{-\tau_t/2}^{\tau_t/2} d\hat{t}' e^{i \left[S_m^0 \theta' - (H\sigma S_m^0 + k)\omega_t \hat{t}'\right]}$$

$$a_{k,m,\sigma}^{G} = \frac{1}{\tau_{b,t}} \int_{-\tau_{b,t}/2}^{\tau_{b,t}/2} d\hat{t}' e^{i \left[S_m^0 \theta' - (H\sigma S_m^0 + k)\omega_t \hat{t}' + W'\right]} \frac{\mathbf{v_d}(\mathbf{r}', \theta') \cdot \nabla}{i\omega}$$

we had:

$$\tilde{n}_{a} = \left(\int J_{0}hd^{3}\mathbf{v}\right)^{circ} = -\frac{\pi}{2}e_{a}v_{th}^{3}\sum_{m}\int_{0}^{b_{min}(r^{0})}\frac{d\Lambda}{b(r,\theta)\sqrt{1-\frac{\Lambda}{b(r,\theta)}}}\int_{0}^{\infty}dY\sqrt{Y}\cdot\sum_{k}\sum_{\sigma}\frac{\partial F_{0}}{\partial E}$$
$$\frac{(\omega-\hat{\omega}_{*})e^{-i[S_{m}^{0}\theta-(H\sigma S_{m}^{0}+k)\omega_{t}\hat{t}]}}{\omega-\omega_{D}^{0}-(H\sigma S_{m}^{0}+k)\omega_{t}}\cdot J_{0}^{2}\left[a_{k,m,\sigma}\phi_{m}(r^{0})-(a_{k,m,\sigma}-a_{k,m,\sigma}^{G})\psi_{m}(r^{0})\right]$$

write down equations for one toroidal harmonic and three poloidal harmonics; integrate over velocity space; circulating particles only, v=v_{parallel}, Maxwellian F₀:

contains electrostatic

$$\sum_{m'=m-1}^{m+1} \delta_{m',p} D^{m}(x_{m'})(\phi_{m'} - \psi_{m'}) =$$
waves(sound, drift):
symmetric in Φ and ψ

polarisation terms
$$\begin{pmatrix} P_{m-1} & \tau N^{m}(x_{m-1})\omega_{di}^{+}/\omega & 0 \\ \tau N^{m-1}(x_{m})\omega_{di}^{-}/\omega & P_{m} \\ 0 & \tau N^{m}(x_{m+1})\omega_{di}^{-}/\omega & P_{m+1} \end{pmatrix} \begin{pmatrix} \psi_{m-1} \\ \psi_{m} \\ \psi_{m+1} \end{pmatrix}$$
off-diagonal elements (sidebands)

with

$$\tilde{D}^{m}(x) = \left(1 - \frac{\omega_{*}^{m}}{\omega}\right) x Z(x) - \frac{\omega_{*}^{m}}{\omega} \eta \left(x^{2} + x Z(x)(x^{2} - \frac{1}{2})\right)$$

$$2\tilde{N}^{m}(x) = \left(1 - \frac{\omega_{*}^{m}}{\omega}\right) \left[x^{2} + x Z(x)(x^{2} + \frac{1}{2})\right] - \frac{\omega_{*}^{m}}{\omega} \eta \left[x^{2}(x^{2} + \frac{1}{2}) + x Z(x)(\frac{1}{4} + x^{4})\right]$$

$$P = \tau \left(\Gamma_{0} - 1\right) \left[1 - \frac{\omega_{*}^{*}}{\omega} \left(1 + \eta_{i} \frac{\Gamma_{0}G_{0}}{\Gamma_{0} - 1}\right)\right].$$

$$\omega_d^{\pm} \approx \frac{v_{th,i}^2}{\Omega_i} \frac{1}{R_0} (\frac{m}{r} \pm \frac{\partial}{\partial r}) = \omega_d^n \pm \omega_d^r$$

Assuming a Maxwellian F_0 with $\partial F_0/\partial E = -F_0/T$ and using

$$\int_0^\infty \frac{dt \ e^{-t^2}}{x_m^2 - t^2} = \frac{-\sqrt{\pi}Z(x_m)}{2x_m}; \qquad \int_0^\infty \frac{dt \ t^2 \ e^{-t^2}}{x_m^2 - t^2} = \frac{-\sqrt{\pi}}{2}(x_m + x_m^2 Z(x_m))$$

where

$$x_m = \frac{\omega}{|k_{\parallel,m}|v_{th}}; \qquad t = \frac{v_{\parallel}}{v_{th}}; \qquad v_{th} = \sqrt{\frac{2T}{m}}$$

Hamiltonian description:

the Lagrangian $\underline{\hat{\Gamma}}(\mathbf{x}, \mathbf{p}, t) = \mathbf{p} \cdot d\mathbf{x} - \hat{H}dt$, the Hamiltonian $\hat{H}(\mathbf{x}, \mathbf{p}, t) = \frac{|\mathbf{p} - eA|^2}{2m} + e\phi$. Hamilton's equation of motion:

$$\frac{d\mathbf{x}}{dt} = \partial_{\mathbf{p}}\hat{H} = \mathbf{p}/m$$
$$\frac{d\mathbf{p}}{dt} = -\partial_{\mathbf{x}}\hat{H} = e(\mathbf{E} + \mathbf{v} \times \mathbf{B}) + e\frac{d\mathbf{A}}{dt}$$

the physics of a system is conserved under a coordinate transform if there exists a total derivative dS: $\underline{\Gamma}'(\mathbf{Z}',t) = \underline{\Gamma}(\mathbf{Z},t) + dS$

$$\begin{aligned} (\mathbf{x}, \mathbf{p}) &\to (\mathbf{X}, \mu, v_{\parallel}, \gamma) \\ \underline{\hat{\Gamma}} &\to \underline{\Gamma}_{\mathrm{gc}} = \mathbf{A}_{(0)}^* \cdot \mathsf{d}\mathbf{X} + \mu \mathsf{d}\gamma - H_{\mathrm{gc}}\mathsf{d}t \\ &\text{with } H_{\mathrm{gc}} = \frac{1}{2}mv_{\parallel}^2 + \mu B_{(0)}(\mathbf{X}) + e\phi_{(0)}(\mathbf{X}), \end{aligned}$$

Hamiltonian description: action angles

due to guiding centre transformation, canonicity of coordinates (X, E, μ, γ) is lost it is possible to find action angles, i.e. canonical variables for periodic systems:

$$\dot{\mathbf{J}} = -\frac{\partial H_{(0)}}{\partial \boldsymbol{\alpha}} = 0, \quad \dot{\boldsymbol{\alpha}} = \frac{\partial H_{(0)}}{\partial \mathbf{J}}$$

motion is separated into 3 periodic motions:

$$\boldsymbol{\alpha} = (\alpha_1, \alpha_2, \alpha_3) = \boldsymbol{\Omega} \ t = \boldsymbol{\alpha}_0 + \boldsymbol{\Omega} \int_0^{\theta} \frac{d\theta}{\dot{\theta}}$$

 $\begin{array}{rcl} \Omega_{1} & = & \Omega_{b} \oint \frac{d\theta}{2\pi} \frac{1}{\dot{\theta}} \dot{\gamma} & \approx & \Omega_{b} \oint \frac{d\theta}{2\pi} \frac{1}{\dot{\theta}} \frac{eB_{(0)}}{m} & \text{gyromotion} \\ \\ \Omega_{2} & \equiv & \Omega_{b} = 2\pi \left(\oint \frac{1}{\dot{\theta}} \right)^{-1} & \approx & 2\pi \left(\oint \frac{1}{\mathbf{b}_{(0)} \cdot \nabla \theta} \frac{1}{v_{\parallel}} \right)^{-1} & \text{poloidal bounce frequency} \\ \\ \Omega_{3} & = & \Omega_{b} \oint \frac{d\theta}{2\pi} \frac{1}{\dot{\theta}} \dot{\varphi} & \approx & \Omega_{b} \oint \frac{d\theta}{2\pi} \frac{1}{\dot{\theta}} \mathbf{v}_{D} \cdot \left[-q'(\bar{\Psi})\theta \nabla \Psi + \nabla(\varphi - q(\bar{\Psi})\theta) \right] \\ & \quad + \delta_{\text{passing }} q(\bar{\Psi})\Omega_{b} & \text{toroidal precession frequency} \end{array}$

explicit motion of particles

$$\begin{split} \dot{\Psi} &= \mathbf{v}_{g} \cdot \nabla \Psi & \mathbf{v}_{g} = \mathbf{v}_{\mathbf{E} \times \mathbf{B}} + \mathbf{v}_{\nabla B} + \mathbf{v}_{c} \\ \dot{\theta} &= v_{\parallel} \mathbf{b} \cdot \nabla \theta + \mathbf{v}_{g} \cdot \nabla \theta \\ \dot{\varphi} &= v_{\parallel} q \mathbf{b} \cdot \nabla \theta + \mathbf{v}_{g} \cdot \nabla \varphi \end{split}$$

lowest order:

$$\begin{split} \Omega_{2}^{-1} &= \oint \frac{d\theta}{2\pi} \frac{1}{\mathbf{b} \cdot \nabla \theta} \frac{1}{v_{\parallel}} \text{ with } \mathbf{b} \cdot \nabla \theta \approx 1/qR. \qquad \Omega_{2} = \Omega_{b} = \pm \frac{1}{qR_{0}} \sqrt{\frac{2\mathsf{E}}{m}} \bar{\Omega}_{b}. \\ \bar{\Omega}_{b} &= \left(\oint \frac{d\theta}{2\pi} \frac{1}{\sqrt{1 - \lambda(1 + \epsilon \cos \theta)}} \right)^{-1} \text{ with } \lambda = \mu B_{0}/\mathsf{E} \\ \bar{\Omega}_{b}^{-1} &= \sqrt{\frac{2\epsilon + (1 - \epsilon)\kappa^{2}}{2\epsilon}} \oint \frac{d\theta}{2\pi} \frac{1}{\sqrt{1 - \kappa^{2} \sin^{2}(\theta/2)}} \text{ with } \kappa^{2} = 2\epsilon\lambda/[1 - (1 - \epsilon)\lambda] \end{split}$$

leads to elliptic integrals for bounce/passing and precessional particle motion [circular, large aspect ratio: Coppi, Rewoldt, 1980]

QN:
$$\sum_{j} e \left[\int J_0 h d^3 \mathbf{v} + \frac{e n_0}{T} e^{-\chi} I_0(\chi) \left[\psi - \phi - \left(1 + \eta G_0(\chi) \right) \frac{\omega_*}{\omega} \psi \right] \right] = 0$$

with

$$\omega_* \equiv \left[\frac{cT\mathbf{b}}{ieB} \times \frac{\nabla n}{n} \cdot \nabla\right]; \qquad \eta \equiv \frac{\nabla T}{T} / \frac{\nabla n}{n}$$
$$\chi \equiv \frac{v_{th}^2 k_{\perp}^2}{2\Omega^2}; \qquad G_0(\chi) = -\chi + \chi I_1(\chi) / I_0(\chi)$$

GKM:

$$-\frac{\omega^{2}}{\omega_{A0}^{2}}\nabla_{\perp}\frac{\hat{n}B_{0}^{2}}{\mathbf{B}^{2}}\nabla_{\perp}\psi + \nabla(\nabla_{\parallel}\psi)\times\mathbf{b}\cdot\nabla(\frac{\nabla\times\mathbf{B}_{0}}{B}) + (\mathbf{B}\cdot\nabla)\frac{(\nabla\times\nabla\times\nabla_{\parallel}\psi)\cdot\mathbf{B}}{B^{2}} + \\ + \mu_{0}P_{0}\frac{\mathbf{b}}{B}\times\left[(\mathbf{b}\cdot\nabla)\mathbf{b} + \frac{\nabla B}{B}\right]\cdot\nabla\left[\frac{\nabla\hat{P}}{B}(\mathbf{b}\times\nabla)\psi\right] = 0 \qquad ($$

$$\mu_{0}\nabla P_{1}\cdot\nabla\times\frac{\mathbf{B}}{B^{2}} \qquad \qquad \text{with } \mathbf{P}_{\mathbf{l}} = \frac{\nabla P}{i\omega B}\left(\mathbf{b}\times\nabla\right)\psi$$

reduced MHD expression!



Für unsere Testteilchen der Geschwindigkeit chwird der erste Term einer ung entsprechen und der zweite der Aufweitung der Geschwindigkeitsverteilung. etrachten wir nu**catoki ale Teynamicale feiction**w**Gœgfficients**rauf



Faltung über die Verteilungsfunktion dieser Teilchen.

ente parallel und eine Komponente senkrecht²49 . Entsprechend**forggle out of**splanærtproz d die Beziehung

 $\frac{\delta u_{\perp}}{\delta u_{\parallel}} = \delta u \cos \frac{\chi}{2} \cos \theta = 2u \sin \frac{\chi}{2} \cos \frac{\chi}{2} \cos \theta,$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -\delta u \sin \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -2u \sin^{2} \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -2u \sin^{2} \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -2u \sin^{2} \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -2u \sin^{2} \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}{\delta u_{\parallel}} = -2u \sin^{2} \frac{\chi}{2} = -2u \sin^{2} \frac{\chi}{2}$ $\frac{\delta u_{\parallel}}$

ente hat ein<u>en Verm</u> (v.), fer nach auftretenden VIntegrationen den gleichen barallelen Komponen Integral berechnen wir mit 8.23 Jund erhalten daraus: digkzitsänderung im Schwerpunktsystem.

otkerde Introloksänderigt gelosi Strößer zwis Strenweinkelnge Treitelten undet Mer Selschwindig-Ind Singer isterister and iculard icontribution avanisher ander ung gemittelt über alle möglichen Streuwinkel berechnen. Da

 Te impuisancerung in senkrechter michtung verschwindet wegen der Abhangig n Degrametrichen ich zünstutsich also beschreiben als Streuung eines Teilchen der Masse nem einem raumfesten Zentrum übig Geschven diskeitsänder zug von Teilchen 1. der Stofspro den Stofskann man mithilfe der Beziehung eine seinen diskeiten dirent der miert durch Stofspro den Stoß kann man mithilfe der Beziehung geschwindigkeit durch den erfolgt mit cher zu behandeln war. Die Umrechnung in das Laborsystem erfolgt mit und die Relativgeschwindigkeit durch π $m_1v_1 + m_2v_2$ 8.10der *mittlere Impulsübertrag* auf Teilchen 1 im Laborsystem gegeben surch Weiterhin wichtig ist die *reduzierte* $\overset{Masse}{\mathbf{u}} = \mathbf{v}_1 - \mathbf{v}_2$. aus dem Schwerpunktsystem ins Laborsystem zurückreichnen. Und $U_{\mu_m} = \frac{V_1}{V_{m_m}} \frac{V_2}{V_m} \frac{V_2}{V_m}$ 8.6 und 8.7 gilt für die Energieänderung: Weiterhin wichtig ist die *reduzierte* $Masse^{\mu_r -} m_1 + m_2$ ittler \mathcal{F}_{2}^{48} $\mathcal{F}_{2}^{m_1}$ $\mathcal{F}_{2}^{m_1}$ $\mathcal{F}_{2}^{m_1}$ $\mathcal{F}_{2}^{m_1}$ $\mathcal{F}_{2}^{m_1}$ $\mathcal{F}_{2}^{m_2}$ $\mathcal{F}_{2}^{m_1}$ $\mathcal{F}_{2}^{m_2}$ $\mathcal{F}_{2}^{m_2}$ Das burgerahzerfällteinarvei Teilerenen den er er stateveit gräßer ist als der zweiter Es ist nämlethächterenzie einer der und sinder und sinder in der inder sinder in der inder sinder auf der sinder sinder einer sinder einer sinder einer sinder sinder sinder sinder einer sinder sinder sinder sinder sinder sinder sinder einer sinder si Staßterne den Boltzmann-Gleichung von sind die Imputsbeträge der beiden Teilcher IFCA beregenen wir die Gleichung von ander sind die Imputsbeträge der beiden Teilcher Die schwabeigkener verteinen berechnen Streuphozesse hänen att spratter werteilungs-ente übreizzwire ander merteilungs-funktion weich Tewire Federation über den Azimut. Di funktion verteiner schwaben hier also die Herleitung des Wirkungsquerschnitts der proponenten senkrecht zu ergeben den selben Wert. Mit 8_24 ist dieser ge chNach 7.27 ist die Rate der Streuprozesse die lieft Endgeschwindig seiten nuktsystem. Ganz analog erhalten wir für den Term in paralleler Richtung von ändern, nicht aber der Betrag. Ganz analog erhalten wir für den Term in paralleler Richtung von ändern, nicht aber der Betrag. Ganz analog erhalten wir für den Term in paralleler Richtung sind die Impulsbeträge der beiden Te ImdSchwerpunkterstein sindereifen für asymstotischage Faller Berden Dabei ist die Wahrscheinigen Gielenzeitig transformieten wir den Ausuriek mithilfe von

koolen en hel Gizgi in in the source of the

wegen der funktionalen Ähnlichkeit mit dem elektrostatischen Potential einer Die Ableitung vond untsprichtungevend zenzioneren einer seutendegie einem 25 au 16813 Die Fu rteilung, eine Potential inktion definiert als u

nennt man bis auf Kenstanten **Eaner Kyserbruch zoer huns** Prentieder Wisigs 338 erhalte Ing voll die zeitliche *Impulsänderzen*diche Treptelächdepung des Testteilchens: Mit der Funktion

Die Ableitung von entspricht in dieser Analogie einem Kraftfeld, Die Funktion, 8.37 8.37 Wiederminist die Rotentration ktion (und? wie in 8.36 wie here Ableitung auf. Die mittlere usammen mit der Funktion 8.38 .39 lere Strates gegeben durch: 8.38 .38 .38 .39 lere 8.38

Um den Energieübertung auch Frechnen müsser wir überne 2,9 ninterrieren Wirserstrütegrieren bis auf Konstanten, hose minute Prentrale Wirsers 2,9 ninterrieren Wirserstrütegrieren die Schwerpunktsgeschwarzening des seitenterrieren wir also für e Impulsander und des Schertenterrieren wir also für ennt die zeitliche Ampulsanstening des seitenter Reptentiale. Mit 8.28 erhalten wir also für ieUnit lichne Impilsendermen der Techerkeltungegral über 26 auf seiter Komponent (19 von 2000 -

nen. Analytische Ausdrücke folgen da Gaschwine iskeit dass das Testteilahsführt karen der Rest Maxwell-Verteilung wechsetwirfaxwellian distriction für die schwindiskeitskeseppnenten schreide Nehmen wir also an, das HintergrundplasmaientbeiellexDicheteten umdedhälfenweislategrale, die sich n Hierast Bud hur also an, das HintergrundplasmaientbeiellexDicheteten umdedhälfenweislategrale, die sich n schen Geschwindigkeit des Plasmas, Für die benötigten Ableitungen gilt: gegeben auszh, wobei für das Verhältnis von Testteilenengeschwindigkeitazut. Dermischeihende Geschwindigkeit des Hintergrungplasmasstent. s. B.40 =1/vth Vurden explizitent sich und in weiter im auf das resttendnen und 2 auf die righergindie =1/vth Vurden explizitentialfühlter inden in das resttenden vielen und 2 auf die right über Plasmaspezies: Das American einer steht vereinfachere, vinder man die Integrate über Mit werkel offentialfühlt in Statt und demen hest weeder in zweisintegrale über für die Anderungsrate der Energie des Tritlerfühlte damen ein best weeder in Zweisintegrale über für die usdrucke für Impuls- und Energie des Tritlerfühlte damen ein hest weeder in Gas im thermischen Gleichgewi usdrucke für Impuls- und Energie des Tritlerfühlter wie sie im letzten Abschnift behöndelt under explizit ausrechnen. unden, explizit ausrechnen. unterscheiden, und sich in ein beschränktes IntegrätzusammenfalsenlassenlassenhElpsisterfalGeschwindigkeit Mit der Potentialfunktion. 8.44 und deren Ableitung 3.47. folgt aus ELL für die ren ist aus der Elektrostatik bekannt. Das ventenbeschwindegkeitistes Blassnas: Enktron benötigten A *nderungsrate der Energie des Teilchenstrahls* die Beziehung bekannt S. B.40 wobei dadurch noch beliebige Kombinationen von Strahl- und Plasmaspezies abgedeckt aus der Klammer Azfaus und^uerhälten nach einer Könnenformung*Grückentellgem Pietgültigenktion* b Für uns wichtige Eigenschaften sind: Aussiguten der Ebenevsigerkonschultrine Teilchestraunchunin Phesmalisizierte a Blauert nd. Wir fassen die Terme zusammen, ziehen den Faktor ∂F_1 us der Klammer heraus und erhalten nach (<u>eine</u>) Umformung einen algemeingen filtigen 1 d = 1usdruck für den Energeeübertrag auf ein Teilchen durch ein thermalisiertes Plasma:Anhandsvon Able Sérver a kar för der Sieher i Sieher Sieher Sieher Sieher Sieher Strennsung schnel-er stleichteschwi Pligsein strufflesoms Bäzer file fienörigte wich bliet Fingektigde: 8.51 Advanced Courses EP, 2020