# Non-linear Simulation of Edge Localized Modes in ASDEX Upgrade

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Overview Reduced MHD Numerics

### 3 Modelling of ELM Dynamics

Full Crash Resolution Scan ELM Losses/Divertor Heat Load Filament Dynamics

### 4 Summary and Outlook



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### Introduction

### Tokamak





- magnetic field in toroidal direction created by toroidal field coils
- inductively driven plasma current creates poloidal magnetic field
- $\rightarrow$  plasma confinement by helically winding field lines

# Introduction

# Edge Localized Modes







S. Pamela. Ph.D. thesis, University of Provence (2010)

- relaxation-like oscillatory instability at the boundary of H-mode plasmas (pedestal collapse)
- driven by large pressure gradients and current densities
- eject particles and energy on very short time-scales
- plasma particle and energy content decreased by up to 10%
- high heat loads on plasma-facing components (in particular divertor targets)

 $\rightarrow$  comprehensive theoretical understanding necessary for control and prediction of ELM properties



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### JOREK

### Overview



#### SD Non-linear MHD in X-point tokamak geometry

G. Huysmans and O. Czarny. Nucl Fusion, 47, 659 (2007)

- European project
- multi-purpose non-linear MHD code

#### Edge Localized Modes in

- ASDEX Upgrade M. Hölzl, S. Günter, et al. Phys Plasmas, 19, 082505 (2012)
- MAST S. J. P. Pamela, G. T. A. Huysmans, et al. PPCF, 55, 095001 (2013)
- JET S. J. P. Pamela, G. T. A. Huysmans, et al. PPCF, 53, 054014 (2011)
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- ▷ Resonant Magnetic Perturbations M. Bécoulet, F. Orain, et al. Phys Rev Lett, 113, 115001 (2014)
- ▷ Pellet ELM Triggering G. Huysmans, S. Pamela, et al. 23rd IAEA, THS/7-1 (2010)
- Tearing Modes J. Pratt and E. Westerhof. 54th APS (2012)
- Disruptions A. Fil, E. Nardon, et al. Phys Plasmas, 22, 062509 (2015)

▷ ...



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Starting point: resistive MHD equations including particle and heat sources/diffusion

Reduced MHD

$$\begin{split} \partial_{t} \rho + \nabla \cdot (\rho \mathbf{v}) &= \nabla \cdot (D_{\perp} \nabla_{\perp} \rho) + S_{\rho} \\ \rho \left( \partial_{t} + \mathbf{v} \cdot \nabla \right) \mathbf{v} &= -\nabla p + \mathbf{j} \times \mathbf{B} + \mu \Delta \mathbf{v} \\ \partial_{t} p + \mathbf{v} \cdot \nabla p + \gamma p \nabla \cdot \mathbf{v} &= \nabla \cdot \left( \kappa_{\parallel} \nabla_{\parallel} T + \kappa_{\perp} \nabla_{\perp} T \right) + S_{T} \\ \mathbf{E} + \mathbf{v} \times \mathbf{B} &= \eta \mathbf{j} \\ \nabla \times \mathbf{E} &= -\frac{\partial \mathbf{B}}{\partial t} \\ \nabla \times \mathbf{B} &= \mu_{0} \mathbf{j} \\ \nabla \cdot \mathbf{B} &= \mathbf{0} \end{split}$$

▷ Variables:  $\rho$ ,  $\mathbf{v}$ , p,  $\mathbf{B}$  with  $p = R_s \rho T$ 

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### Reduced MHD

Definition of magnetic and velocity vector fields:  $\mathbf{B} := \underbrace{\frac{F_0}{R}}_{e_{\phi}} \mathbf{e}_{\phi} + \underbrace{\frac{1}{R}}_{e_{\phi}} \nabla \Psi \times \mathbf{e}_{\phi}$ ⊳  $\mathbf{B}_{\phi}$ B<sub>pol</sub>  $\text{and} \quad \mathbf{v} := -R \nabla \mathbf{u} \times \mathbf{e}_{\varphi} + \nu_{||} \mathbf{B} \quad \text{with} \quad |\mathbf{B}_{\varphi}| \gg |\mathbf{B}_{\text{pol}}|$ v⊥ Ζ φ R

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### Reduced MHD



Bnol

 $\triangleright \text{ Definition of magnetic and velocity vector fields: } \mathbf{B} := \underbrace{\frac{F_0}{R} \mathbf{e}_{\varphi}}_{R} + \underbrace{\frac{1}{R} \nabla \Psi \times \mathbf{e}_{\varphi}}_{R}$ 

$$\text{and} \quad v := \underbrace{-R \nabla u \times e_{\varphi}}_{v_{\perp}} + \underbrace{\nu_{||} B}_{v_{\parallel}} \quad \text{with} \quad |B_{\varphi}| \gg |B_{\text{pol}}|$$

$$\begin{split} \boldsymbol{\vartheta}_{t}\boldsymbol{\rho} + \nabla\cdot\left(\boldsymbol{\rho}\mathbf{v}\right) &= \nabla\cdot\left(\boldsymbol{D}_{\perp}\nabla_{\perp}\boldsymbol{\rho}\right) + \boldsymbol{S}_{\boldsymbol{\rho}}\\ \mathbf{e}_{\boldsymbol{\varphi}}\cdot\nabla\times\boldsymbol{R}^{2}\Big\{\boldsymbol{\rho}\left(\boldsymbol{\vartheta}_{t}+\mathbf{v}\cdot\nabla\right)\mathbf{v} &= -\nabla\boldsymbol{p}+\mathbf{j}\times\mathbf{B}+\boldsymbol{\mu}\Delta\mathbf{v}\Big\}\\ & \mathbf{B}\cdot\Big\{\boldsymbol{\rho}\left(\boldsymbol{\vartheta}_{t}+\mathbf{v}\cdot\nabla\right)\mathbf{v} = -\nabla\boldsymbol{p}+\mathbf{j}\times\mathbf{B}+\boldsymbol{\mu}\Delta\mathbf{v}\Big\}\\ \boldsymbol{\vartheta}_{t}\boldsymbol{p}+\mathbf{v}\cdot\nabla\boldsymbol{p}+\boldsymbol{\gamma}\boldsymbol{p}\nabla\cdot\mathbf{v} &= \nabla\cdot\left(\boldsymbol{\kappa}_{\parallel}\nabla_{\parallel}\boldsymbol{T}+\boldsymbol{\kappa}_{\perp}\nabla_{\perp}\boldsymbol{T}\right)+\boldsymbol{S}_{T}\\ & \boldsymbol{\vartheta}_{t}\boldsymbol{\Psi} = \boldsymbol{R}[\boldsymbol{\Psi},\boldsymbol{u}]+\frac{\boldsymbol{\eta}}{\boldsymbol{\mu}_{0}}\mathbf{j}-\boldsymbol{F}_{0}\boldsymbol{\vartheta}_{\boldsymbol{\varphi}}\boldsymbol{u} \end{split}$$

 $\triangleright \text{ Definitions: } \omega := \nabla_{\perp}^2 u \text{ and } j := \Delta^* \Psi$ 

 $\label{eq:powerset} \begin{tabular}{ll} \beg$ 

E. Frank, M. Hölzl, A. Lessig, and E. Sonnendrücker. ESAIM Math Model Numer Anal, 49, 1331 (2015)

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 $\mathbf{B}_{\Phi}$ 



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# JOREK Discretization



poloidal plane: 2D Bezier finite elements (C<sup>1</sup>, iso-parametric)

$$\mathbf{P}(s,t) = \sum_{i=0}^{3} \sum_{j=0}^{3} \mathbf{P}_{ij} B_{i}^{3}(s) B_{j}^{3}(t)$$





#### O. Czarny and G. Huysmans. J Comput Phys, 227, 7423 (2008)

ASDEX Up





# **Typical Simulation**





- Construction of polar grid
- Solution of Grad-Shafranov equation on polar grid using input profiles (F<sub>0</sub>, Ψ<sub>bnd</sub>, profiles for T, ρ, FF')
- Construction of flux-aligned X-point grid
- ideal Wall and Bohm boundary conditions
- Fully implicit time integration (GMRES, Physics-based preconditioner, hybrid openMP/MPI parallelization)

### Postprocessing



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### Modelling of ELM Dynamics Full Crash

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### Full Crash Simulation



- ▷ ASDEX Upgrade discharge #29342@4.25s CLISTE reconstruction by Mike Dunne
- $\triangleright$  toroidal modes  $n = 0 \dots 22$  included
- $\triangleright~$  core resistivity in ASDEX Upgrade:  $\sim 1\cdot 10^{-8}\Omega m$
- $\triangleright\,$  core resistivity in simulation: 2.5  $\cdot\,10^{-7}\Omega m$
- about 500,000 cpu-hours on Helios



1.6

#### Modelling **Energy Time-Trace** 1.6e-06 Emag,03 normalized magnetic energy [a.u.] 1.4e-06 mag.04 Emag,05 1.2e-06 Emag,07 Emag,12 1e-06 Emag,19 Pressure (Pa) 8e-07 - 1.000e+04 6e-07 4e-07 7500. 2e-07 0 5000. 0.6 0.8 1.2 1.4 time [ms] 2500. 12000 10000 0.000 8000 pressure [Pa] 6000 4000 2000 0 2.02 2.04 2.06 2.08 2.1 2

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major radius [m]

19

2.12



### **Energy Time-Trace**



Modelling



### **Energy Time-Trace**



Modelling



### **Energy Time-Trace**





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**Resolution Scan** 





- ASDEX Upgrade discharge #31128
- ▷ core resistivity in simulation:  $2.5 \cdot 10^{-7} \Omega m$  (AUG: ~ 1 · 10<sup>-8</sup>  $\Omega m$ )
- $\triangleright~$  high-n components require high grid resolution  $(m=q\cdot n)\to$  linearly not fully resolved

Modelling

**Resolution Scan** 





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# **Resolution Scan**





- ASDEX Upgrade discharge #31128
- ▷ core resistivity in simulation:  $2.5 \cdot 10^{-7} \Omega m$  (AUG: ~ 1 · 10<sup>-8</sup>  $\Omega m$ )
- $\triangleright~$  high-n components require high grid resolution  $(m=q\cdot n)\to$  linearly not fully resolved
- $\,\triangleright\,$  losses converged  $\rightarrow$  non-linearly well resolved



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### Losses/Divertor Heat Load



- $\triangleright~$  main ELM phase for  $t\leqslant$  3ms
- $\,\triangleright\,$  ballooning turbulence for t>3ms
- $\triangleright\,$  particle/energy losses of  $\sim\,10\%$
- asymmetry in divertor heat load
- diamagnetic drift influences heat load asymmetry and ballooning turbulence

F. Orain, M. Becoulet, et al. Phys Rev Lett, 114, 035001 (2015)



Modelling



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Filament Dynamics

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# **Filament Dynamics**







- radial size of filament: ~ 4cm
- poloidal size of filament: ~ 13.5cm

# **Filament Dynamics**







- radial size of filament: ~ 4cm
- poloidal size of filament: ~ 13.5cm

# **Filament Dynamics**







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# **Filament Dynamics**







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# Outlook

# Summary and Outlook

#### Summary

- $\triangleright\,$  high-n components require high grid resolution  $\rightarrow$  computational limits in linear phase/non-linearly well resolved
- ELM losses comparable to experimental observations for type-I ELMs H. Zohm. PPCF, 38, 105 (1996)
- evolution of toroidal Fourier spectrum and pedestal in qualitative agreement with experimental observations

R. P. Wenninger, H. Reimerdes, O. Sauter, and H. Zohm. Nucl Fusion, 53, 113004 (2013)

P. Schneider, E. Wolfrum, et al. PPCF, 56, 025011 (2014)

#### Outlook

- include diamagnetic drifts (act stabilizing on high mode numbers)
- include toroidal rotation and neoclassical viscosity
- identify different ELM types in our simulations as observed in experiments
- further comparison to experimental observations, e.g. pedestal evolution and heat deposition patterns

#### References

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# Backup Slides Diamagnetic Stabilization





- diamagnetic drift terms stabilize high-n components
- intermediate mode numbers become dominant